

Lecture 22: Linear Programming

Michael Dinitz

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601.433/633 Introduction to Algorithms

Introduction

Today: What, why, and just ~~a~~ a taste of how

- ▶ Entire course on linear programming over in AMS. Super important topic!
- ▶ Fast algorithms in theory and in practice.

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- ▶ Fast algorithms in theory and in practice.

Why: Even more general than max-flow, can still be solved in polynomial time!

- ▶ Max flow important in its own right, but also because it can be used to solve many other things (max bipartite matching)
- ▶ Linear programming: important in its own right, but also even more general than max-flow.
- ▶ Can model many, many problems!

Example: Planning Your Week

168 hours in a week. How much time to spend:

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- ▶ Partying (P)
- ▶ Everything else (E)

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 - ▶ Everything else (E)
- ▶ $E \geq 56$ (at least 8 hours/day sleep, shower, etc.)
 - ▶ $P + E \geq 70$ (need to stay sane)
 - ▶ $S \geq 60$ (to pass your classes)
 - ▶ $2S + E - 3P \geq 150$ (too much partying requires studying or sleep)

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Question: Suppose “happiness” is $2P + 3E$. Can we find a feasible solution maximizing this?

Linear Programming

$$C \cdot x \geq s$$

Input (a “linear program”):

- ▶ n variables $x_1, \dots, x_n$ (take values in $\mathbb{R}$)
- ▶ m *non-strict linear inequalities* in these variables (constraints)
 - ▶ E.g.: $3x_1 + 4x_2 \leq 6$, $0 \leq x_1 \leq 3$, $x_2 - 3x_3 + 2x_7 = 17$
 - ▶ Not allowed (examples): $x_2x_3 \geq 5$, $x_4 < 2$, $x_5 + \log x_2 \geq 4$
- ▶ Possibly a *linear* objective function
 - ▶ $\max 2x_3 - 4x_5$, $\min \frac{5}{2}x_4 + x_2$, ...

$$\begin{aligned} \max \quad & 5x_1 + 2x_3 - 7x_7 \\ \text{s.t.} \quad & x_1 - 110x_2 + 1000x_7 \leq -5 \\ & \vdots \end{aligned}$$

Goals:

- ▶ Feasibility: Find values for x 's that satisfy all constraints
- ▶ Optimization: Find feasible solutions maximizing/minimizing objective function

Both achievable in polynomial time, reasonably fast!

Planning your week as an LP

Variables: P, E, S

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$$\max \quad 2P + E$$

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When using an LP to model your problem, need to be sure that *all* aspects of your problem included!

Operations Research-style Example

Four different manufacturing plants for making cars:

	labor	materials	pollution
Plant 1	2	3	15
Plant 2	3	4	10
Plant 3	4	5	9
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- ▶ Need to produce at least **400** cars at plant 3 (labor agreement)
- ▶ Have **3300** total hours of labor, **4000** units of material
- ▶ Environmental law: produce at most **12000** pollution
- ▶ Make as many cars as possible

OR example as an LP

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Four different manufacturing plants for making cars:

Variables: x_i = # cars produced at plant i , for $i \in \{1, 2, 3, 4\}$

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Objective: $\max x_1 + x_2 + x_3 + x_4$

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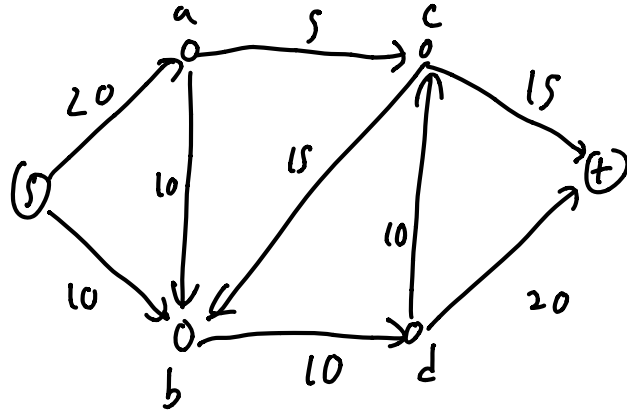
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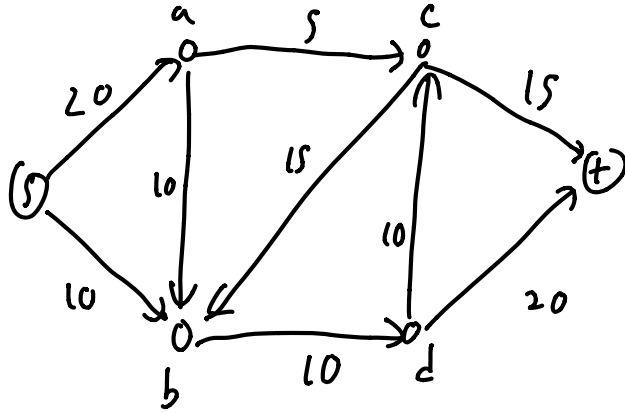
$$x_i \geq 0 \quad \forall i \in \{1, 2, 3, 4\}$$

Max Flow as LP



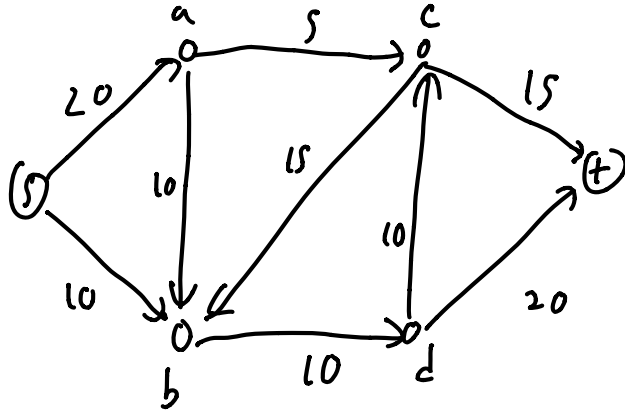
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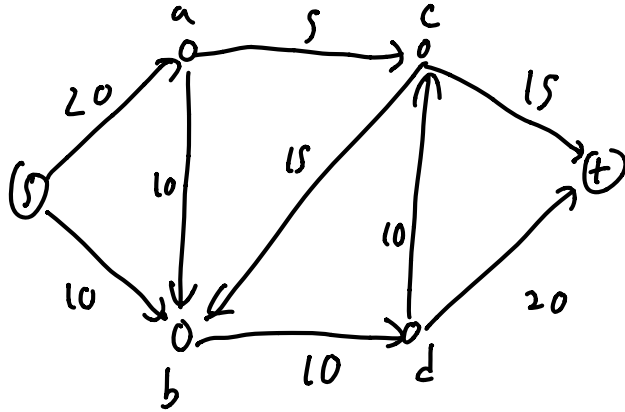
Variables: $f(e)$ for all $e \in E$



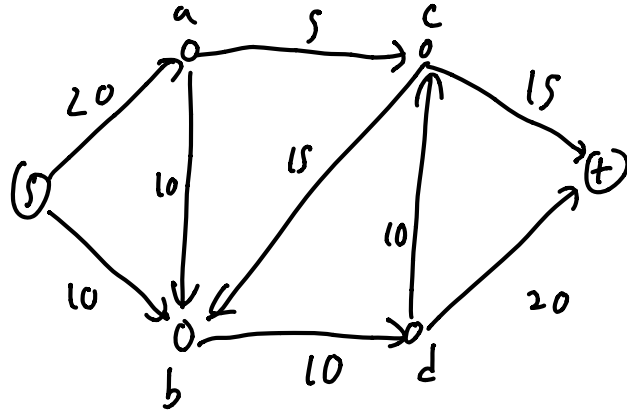
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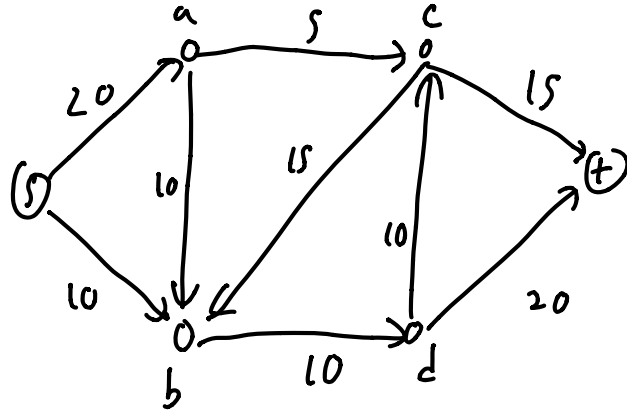
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Objective: $\max \sum_v f(s, v) - \sum_v f(v, s)$

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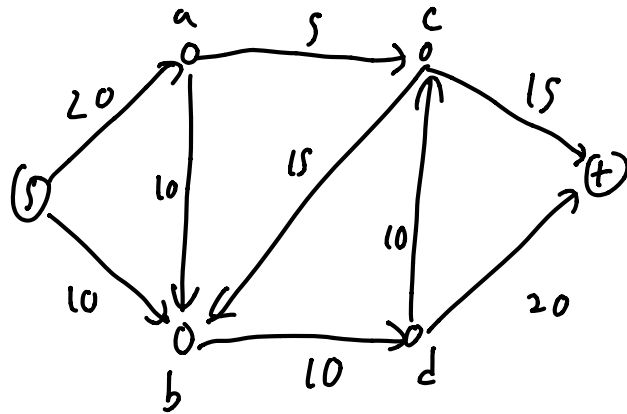


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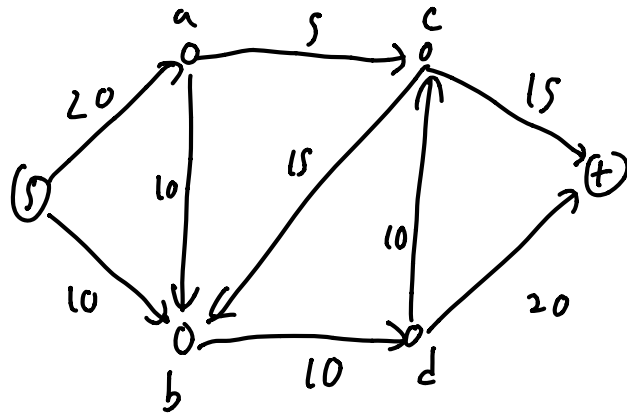
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$$\sum_v f(v, u) - \sum_v f(u, v) \stackrel{<}{=} 0 \stackrel{>}{=} \quad \forall u \in V \setminus \{s, t\}$$

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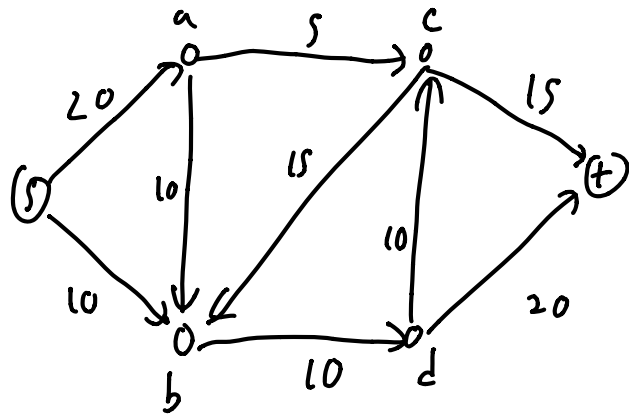
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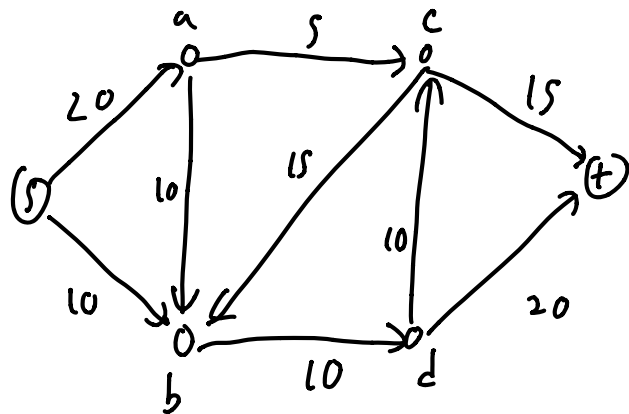
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So can solve max-flow and min-cut (slower) by using generic LP solver

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Generalization of max-flow with multiple commodities that can't mix, but use up same capacity

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Generalization of max-flow with multiple commodities that can't mix, but use up same capacity

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- ▶ Directed graph $G = (V, E)$
- ▶ Capacities $c : E \rightarrow \mathbb{R}_{\geq 0}$
- ▶ k source-sink pairs $\{(s_i, t_i)\}_{i \in [k]}$

Goal: send flow of commodity i from s_i to t_i , max total flow sent across all commodities

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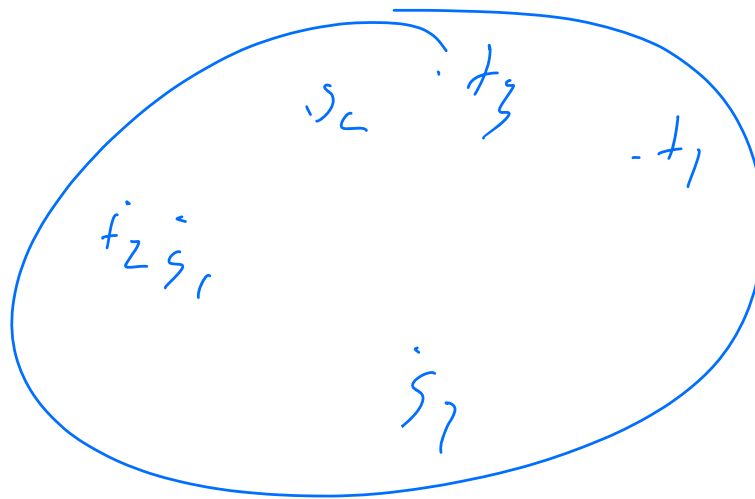
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Flow of commodity i on edge e

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Concurrent Flow

Multicommodity flow, but:

- ▶ Also given *demands*
 $\mathbf{d} : [k] \rightarrow \mathbb{R}_{\geq 0}$
- ▶ Question: Is there a multicommodity flow that sends at least $\mathbf{d}(i)$ commodity- i flow from s_i to t_i for all $i \in [k]$?

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$$f_i(e) \geq 0 \quad \forall e \in E, \forall i \in [k]$$

$$\sum_v f_i(s_i, v) - \sum_v f_i(v, s_i) \geq d(i) \quad \forall i \in [k]$$

Maximum Concurrent Flow

If answer is no: how much
do we need to scale down
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Maximum Concurrent Flow

Variables:

- ▶ $f_i(e)$ for all $e \in E$ and for all $i \in [k]$.
- ▶ λ

Objective: $\max \lambda$

If answer is no: how much do we need to scale down demands so that there is a multicommodity flow?

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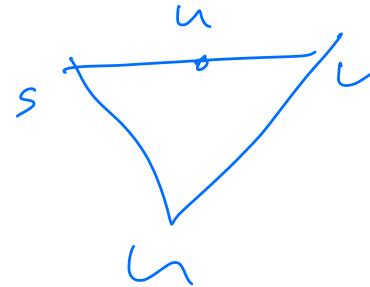
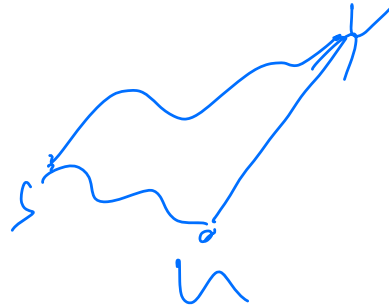
$$\sum_v f_i(s_i, v) - \sum_v f_i(v, s_i) \geq \lambda d(i) \quad \forall i \in [k]$$

Shortest $s - t$ path

Very surprising LP!

Variables: d_v for all $v \in V$: shortest-path distance from s to v

$$\begin{array}{ll}\max & d_t \\ \text{subject to} & d_s = 0 \\ & d_v \leq d_u + \ell(u, v) \quad \forall (u, v) \in E\end{array}$$



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Inductive step: $d_{v_i}^* \leq d_{v_{i-1}}^* + \ell(v_{i-1}, v_i) \leq d(s, v_{i-1}) + \ell(v_{i-1}, v_i) = d(s, v_i)$

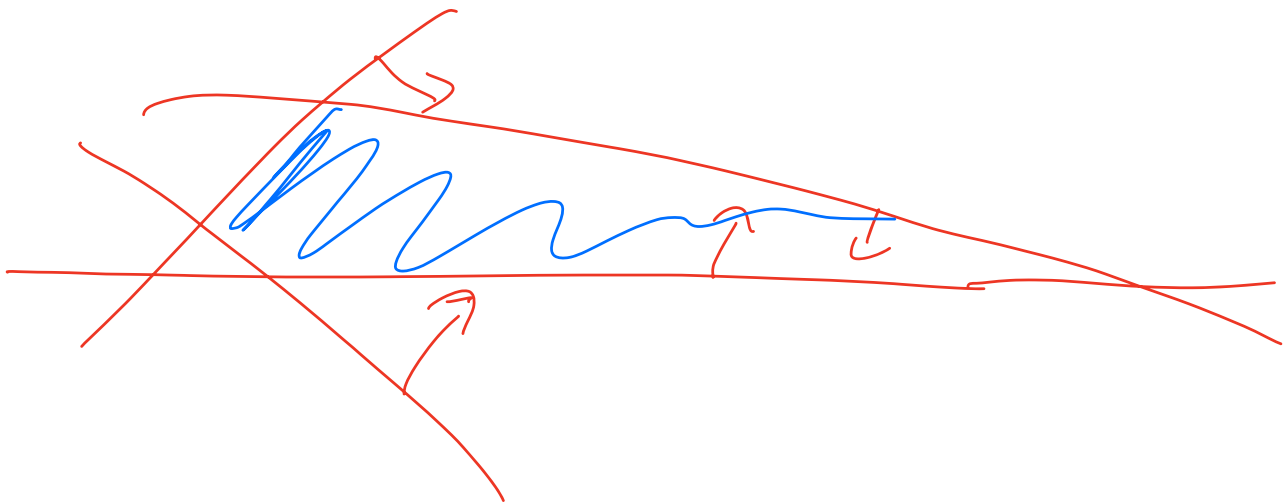
inductive step

Algorithms for LPs

Geometry

To get intuition: think of LPs *geometrically*

- ▶ Space: $\mathbb{R}^n$ (one dimension per variable)
- ▶ Linear constraint: halfspace (one side of a hyperplane)
- ▶ Feasible region: intersection of halfspaces. *Convex Polytope* (usually just called a *polytope*)



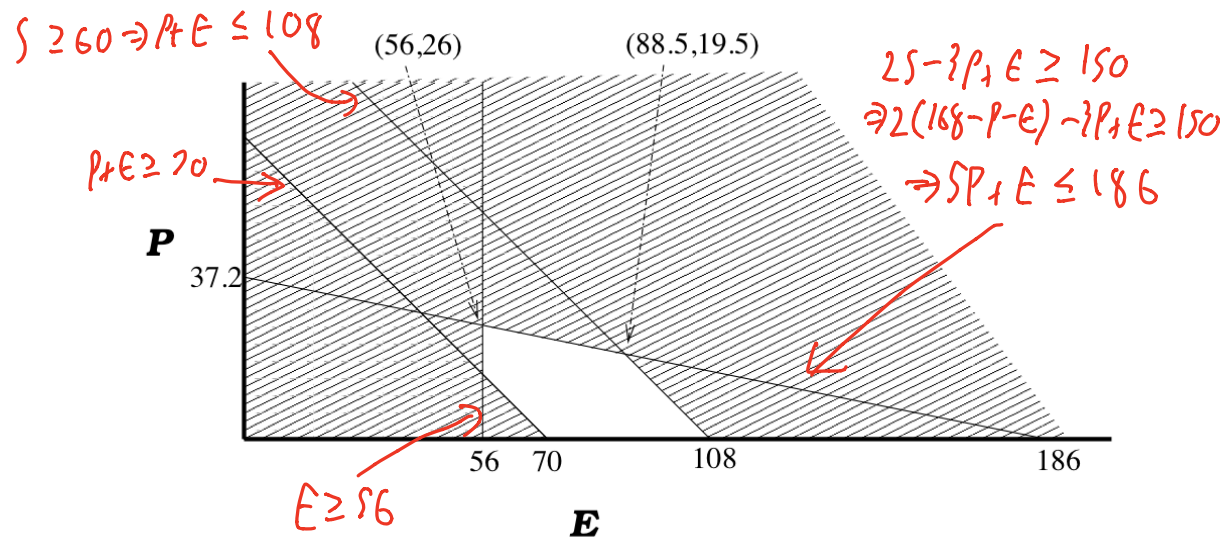
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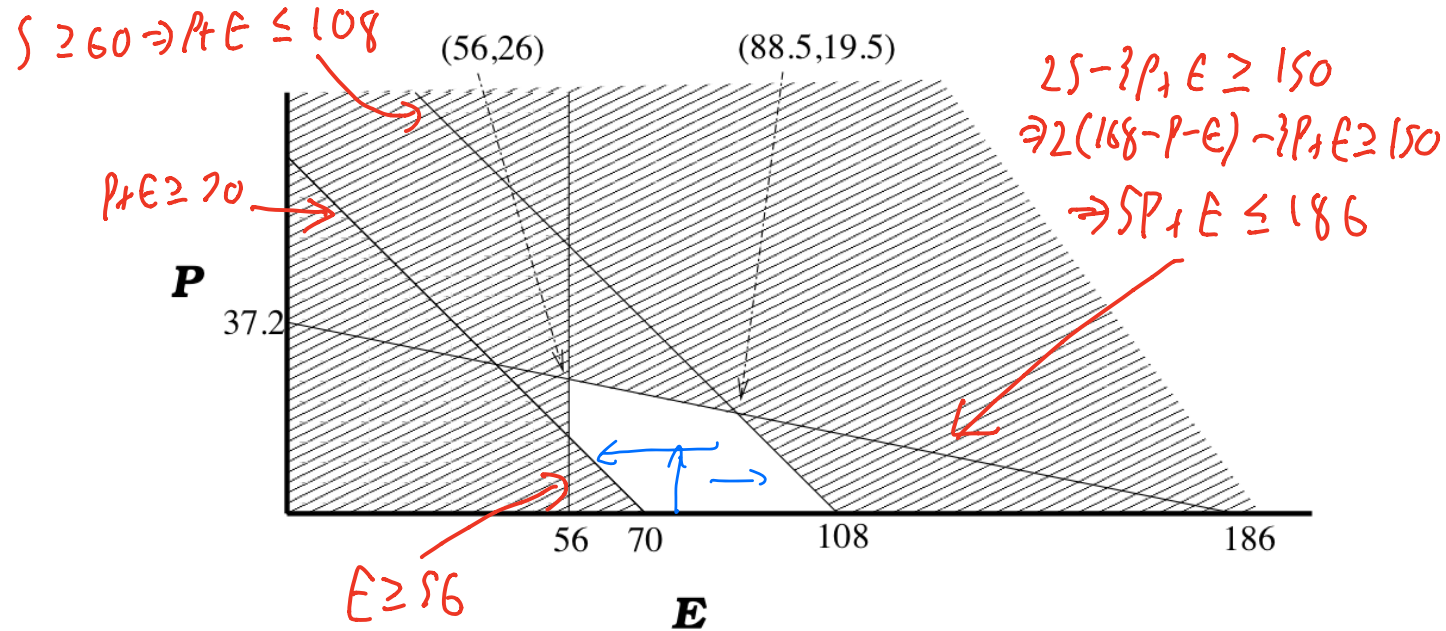
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Example: planning your week

- ▶ 3 variables S, P, E so $\mathbb{R}^3$
- ▶ But $S + P + E = 168 \implies S = 168 - P - E$
- ▶ Make this substitution, get $\mathbb{R}^2$



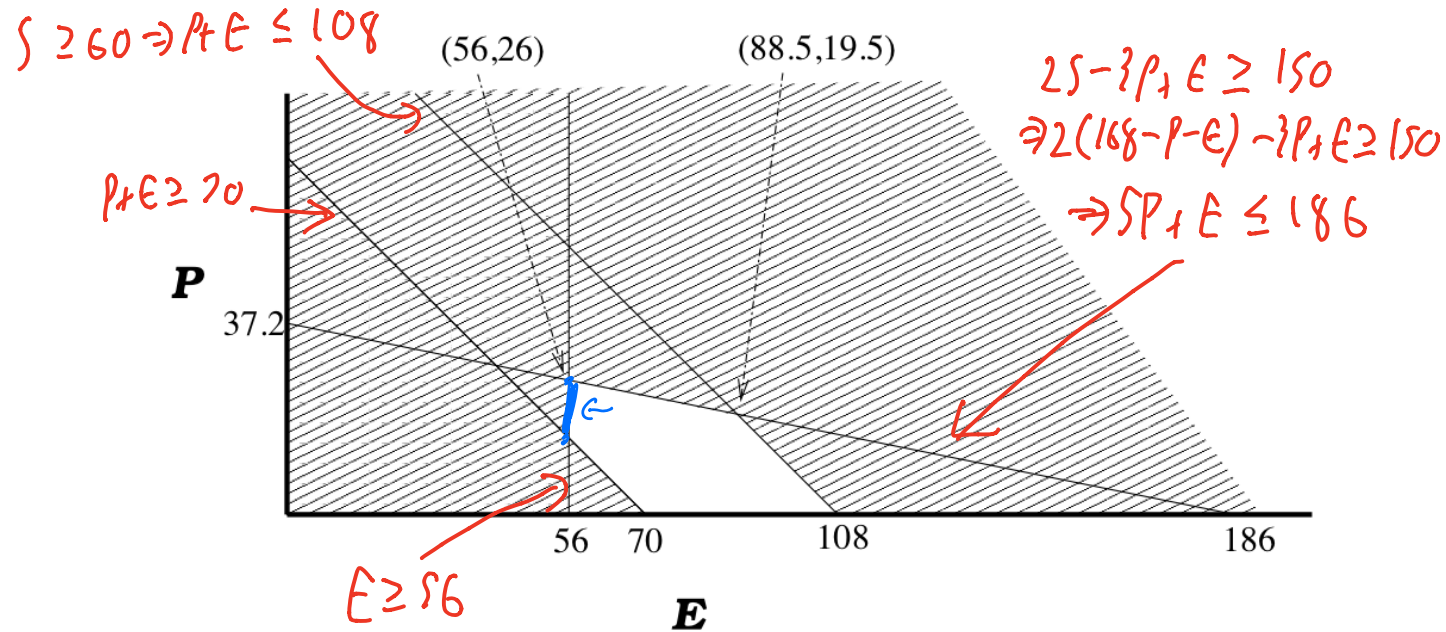
Geometry (cont'd)



Objective: feasible solution “furthest” along specified direction

- ▶ $\max P$: $(56, 26)$
- ▶ $\max 2P + E$: $(88.5, 19.5)$

Geometry (cont'd)



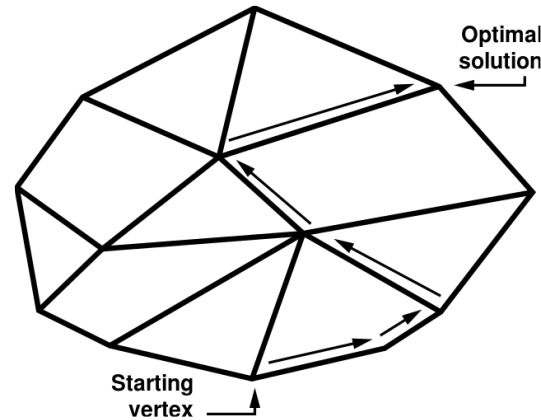
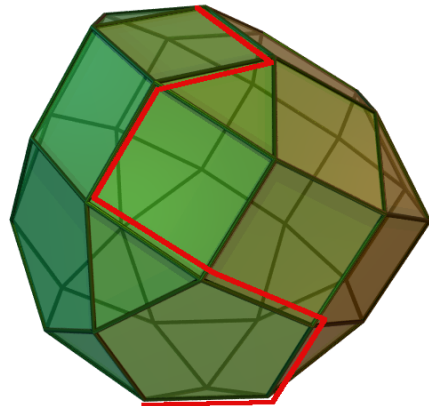
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Main theorem: optimal solution is always at a “corner” (also called a “vertex”)

Simplex Algorithm [Dantzig 1940's]

```
Initialize  $\vec{x}$  to an arbitrary corner  
while(a neighboring corner  $\vec{x}'$  of  $\vec{x}$  has better objective value) {  
     $\vec{x} \leftarrow \vec{x}'$   
}  
return  $\vec{x}$ 
```



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Theorem: Simplex returns the optimal solution.

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- ▶ Fast in practice!
 - ▶ Much of AMS LP course really about simplex: traditionally favorite algorithm of people who want to actually solve LPs
- ▶ Some theory to explain discrepancy (“smoothed analysis”)

Ellipsoid Algorithm [Khachiyan 1980]

First polytime algorithm!

Designed to just solve feasibility question $\implies$ can also solve optimization

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First polytime algorithm!

Designed to just solve feasibility question $\implies$ can also solve optimization

- ▶ Start with ellipsoid E containing feasible region P (if it exists)
- ▶ Let x be center of E
- ▶ While(x not feasible)
 - ▶ Find a hyperplane H through x such that all of P on one side
 - ▶ Let E' be the half-ellipsoid of E defined by H
 - ▶ Find a new ellipsoid $\hat{E}$ containing E' so that $\text{vol}(\hat{E}) \leq \left(1 - \frac{1}{n}\right) \text{vol}(E)$
 - ▶ Let $E = \hat{E}$ and let x be center of $\hat{E}$

Analysis

Extremely complicated!

Geometry of ellipsoids: can always find an ellipsoid containing a half-ellipsoid with at most $(1 - 1/n)$ of the volume of the original

- ▶ Using inequality from last time: after n iterations, volume drops by $(1 - \frac{1}{n})^n \leq 1/e$ factor
- ▶ Crucial fact: if volume “too small”, P must be empty

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In practice: horrible.

Interior Point Methods (Karmarkar's Algorithm)

Fast in both theory and practice!

